

A Gappy POD approach to estimate the wind field in an urban environment for air mobility applications

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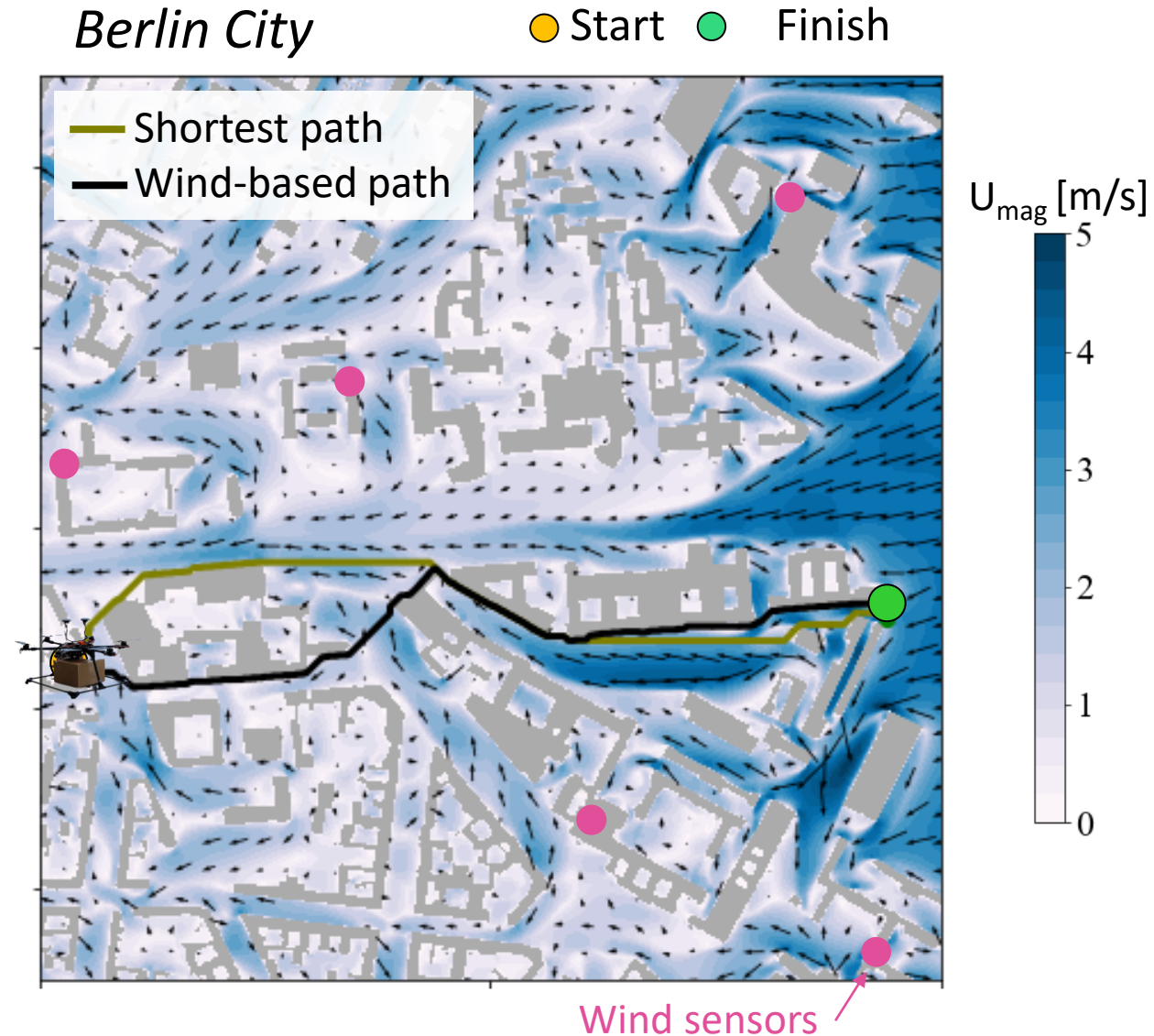
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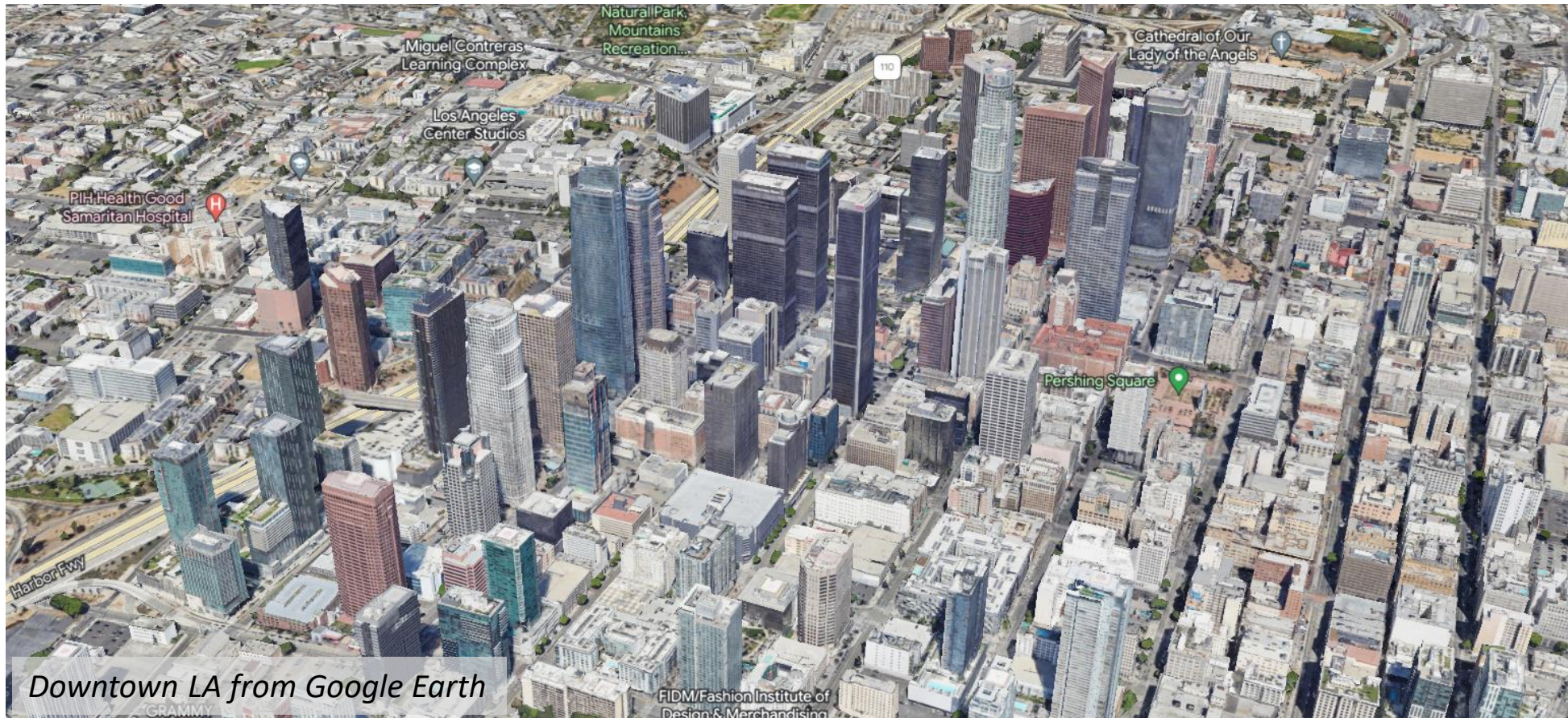
- Real-time wind field estimation from wind sensors for urban air mobility.
- Wind based trajectory optimization: UAVs energy consumption reduced up to 6 %¹.
- Assumption: 2D wind field at a constant wind speed.



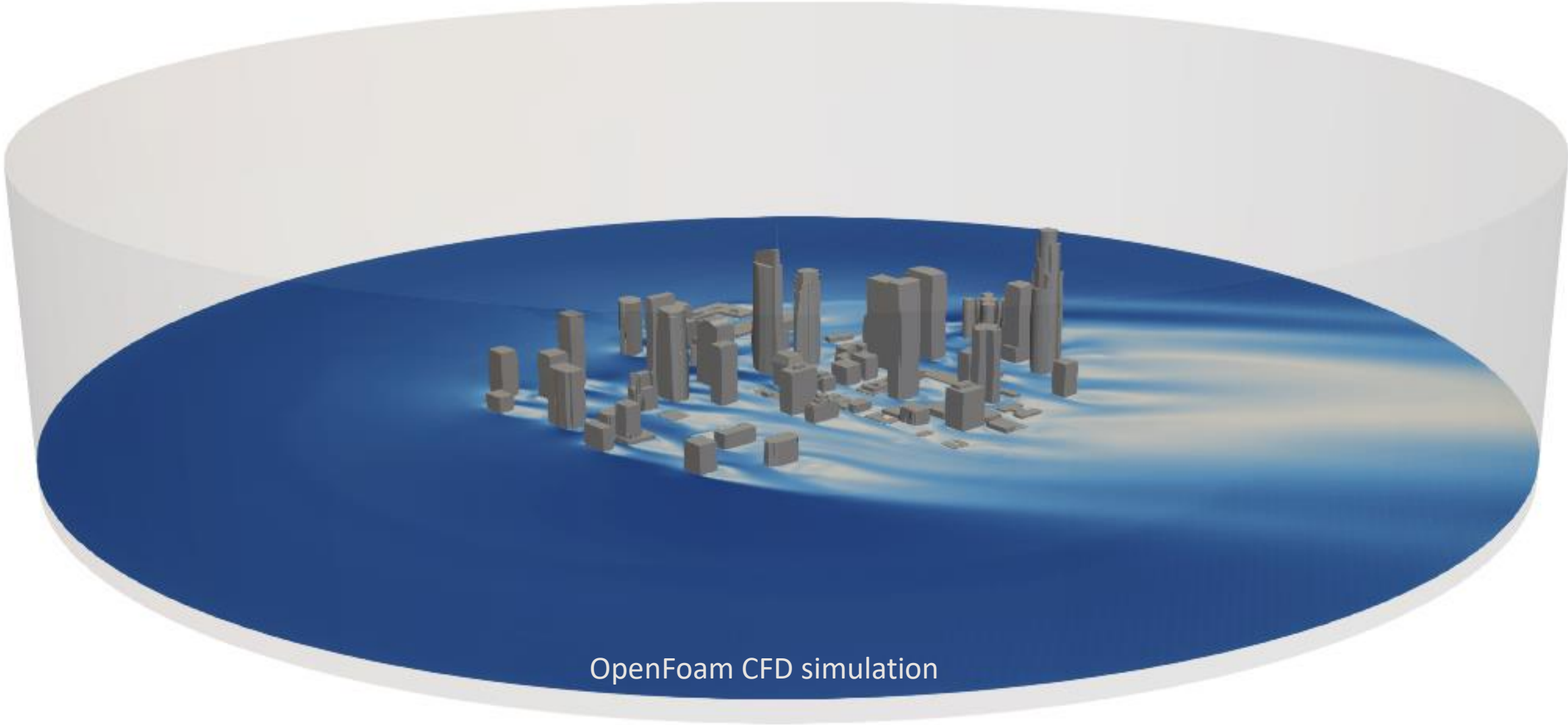
[1] Ebert, C., Weiss, J., Uijt De Haag, M., Ruwisch, C., and Silvestre, J., "Trajectory Planning in Windy Urban Environment – a Gappy POD Approach for Wind Field Estimates with Sparse Sensors," *AIAA Journal* 2023.

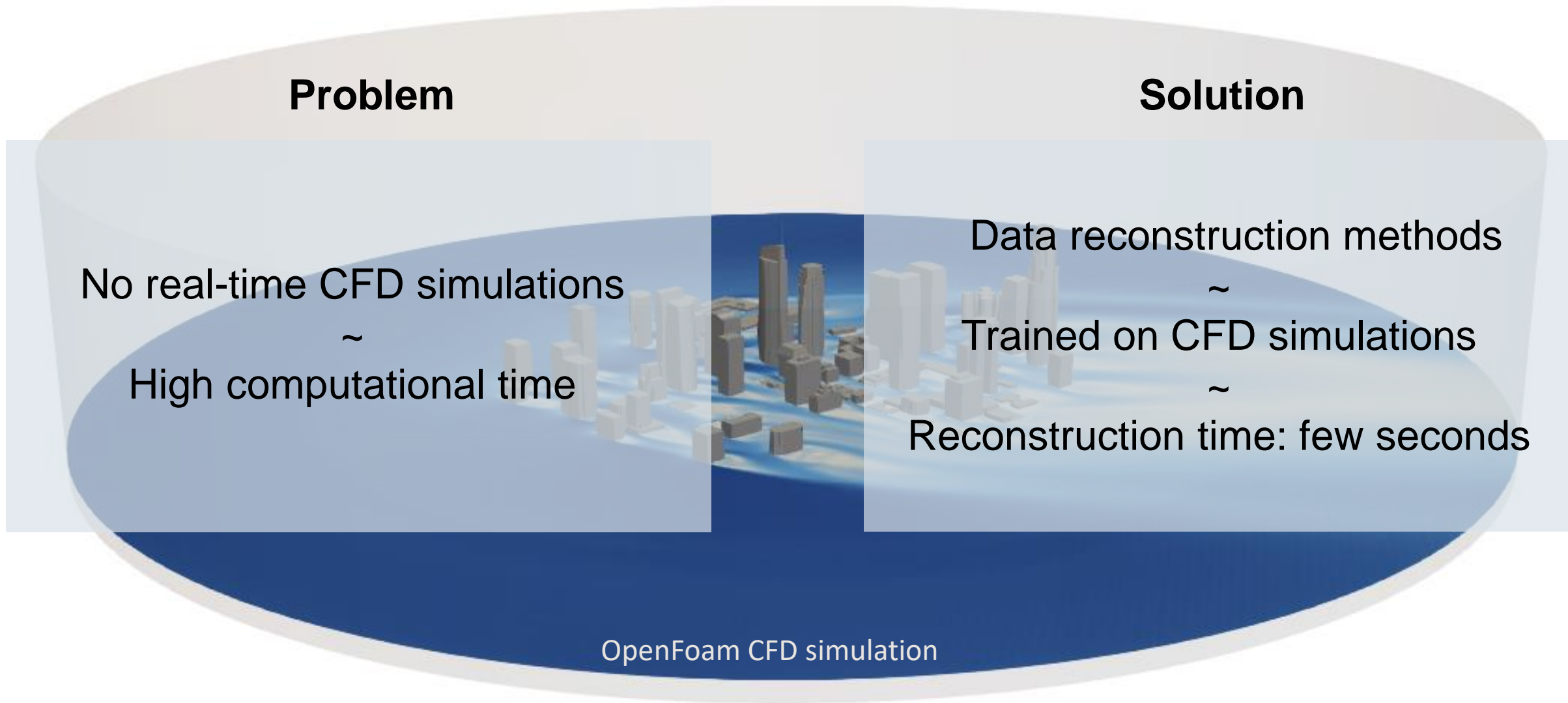
Motivation

- 3D wind field estimation in Downtown Los Angeles
- Different wind speeds U_{ref}



Real-time Wind Field Estimation





- 3D RANS simulations of an urban area for different wind directions and different wind speeds.
- Real-time estimation of an unknown urban wind field with a data reconstruction method.

- Velocity inlet condition: *atmBoundaryLayerInletVelocity*

Final grid ~15 mio. cells

$$U_{\text{profile}} = \frac{u^*}{\kappa} \cdot \ln \left(\frac{z + z_0}{z_0} \right)$$

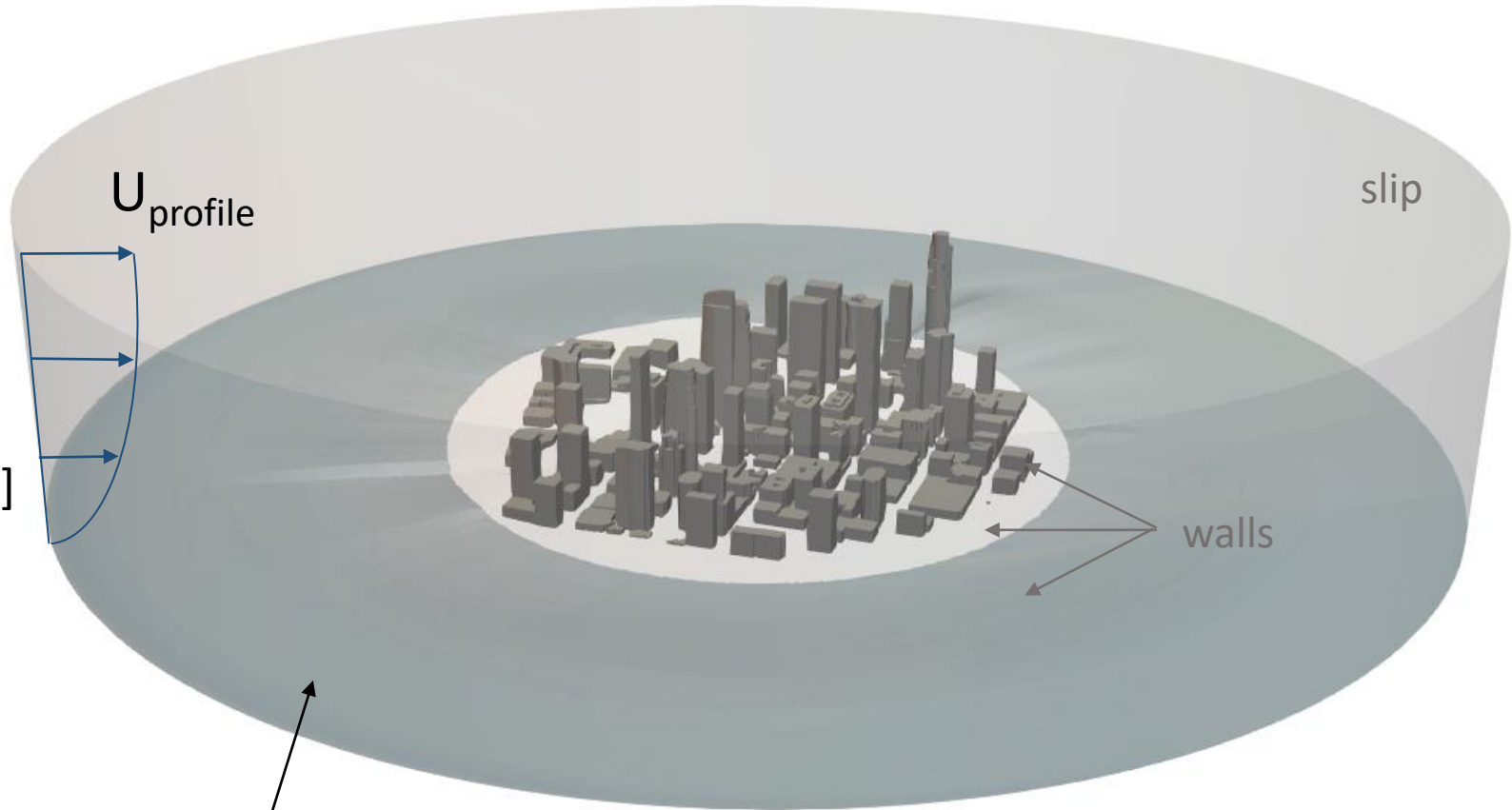
$z_0 = 2$ – Aerodyn. roughness length [m]

U_{profile} - wind speed profile [m/s]

u^* - Friction velocity [m/s]

$\kappa = 0.42$ - von Kármán constant [-]

z - z coordinate [m]



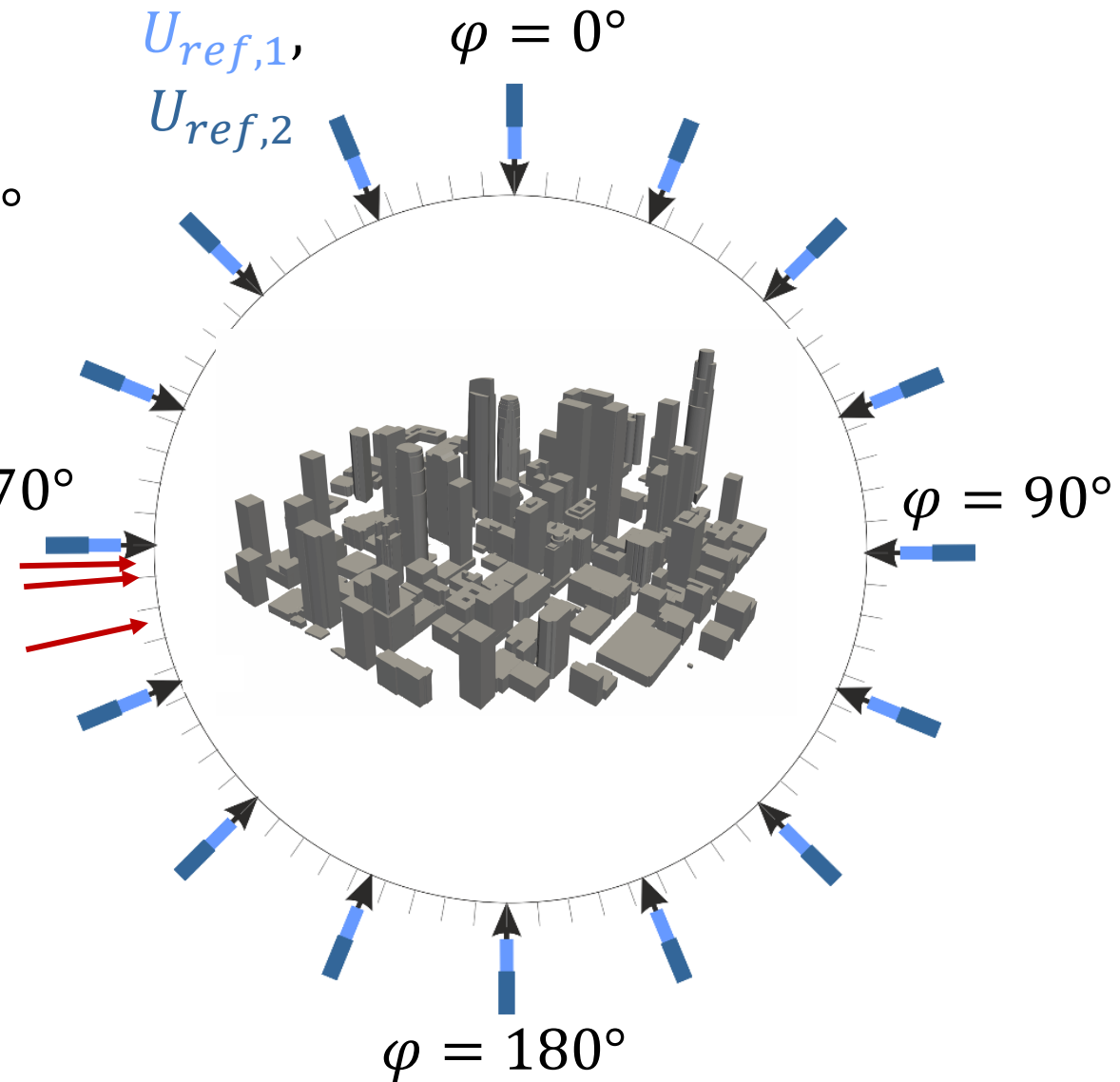
$z_0 = 2$; (Representative for large town centres with a mixture of low-rise and high-rise buildings.)

➤ Data basis:

- 16 Wind directions: $\varphi = 0 - 360^\circ, \Delta\varphi = 22.5^\circ$
- 2 wind speeds @ $z = 310m$:
 - $U_{ref,1} = 8 \text{ m/s}$
 - $U_{ref,2} = 16 \text{ m/s}$

➤ 6 Test cases: (not included in training data)

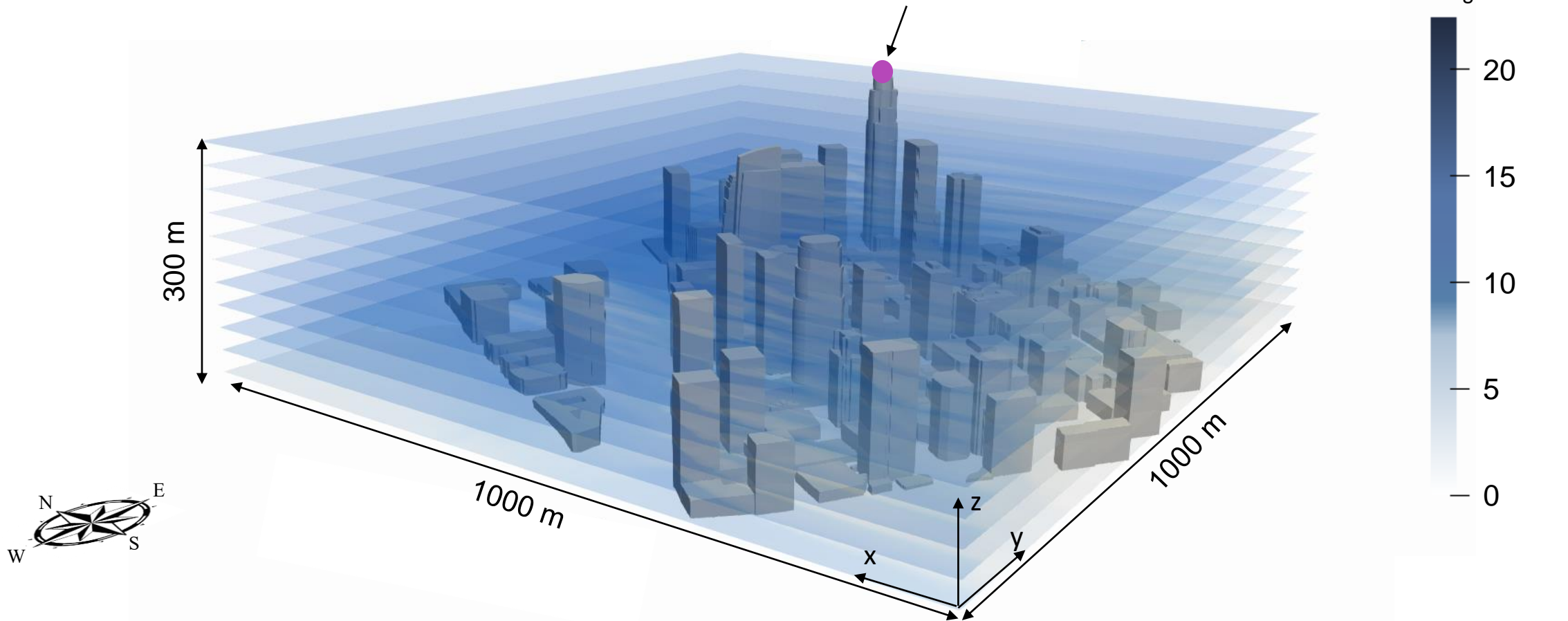
- $\varphi = 259^\circ, U_{ref} = 17, 19, 23, 31 \text{ m/s}$
- $\varphi = 264^\circ, U_{ref} = 31 \text{ m/s}$
- $\varphi = 267^\circ, U_{ref} = 31 \text{ m/s}$



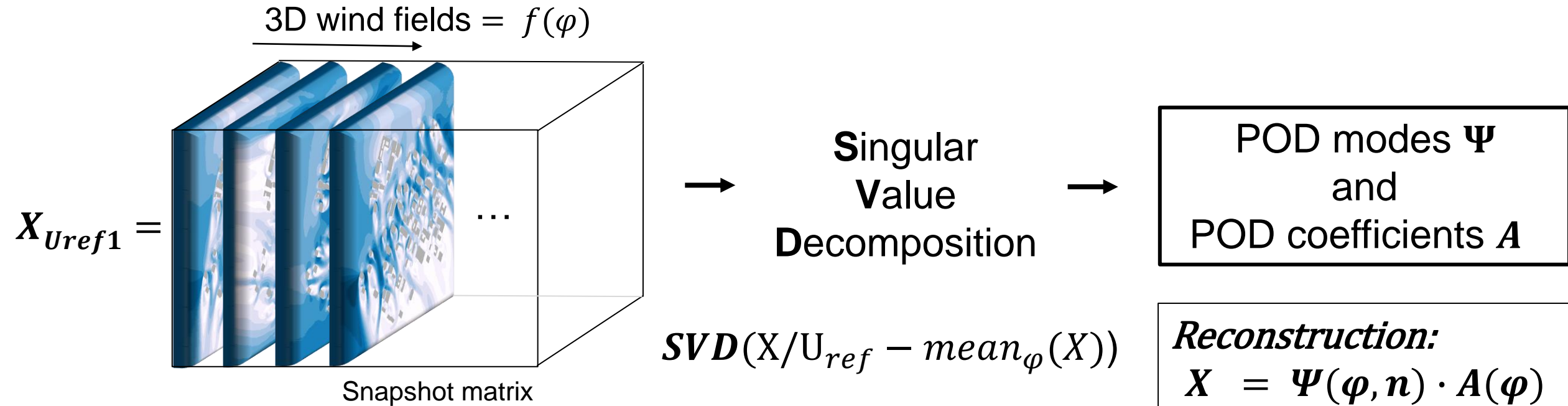
3D Wind Field

- 11 planes at constant heights of $z = 10 \text{ m} - 310 \text{ m}$, $\Delta z = 30 \text{ m}$.
- Horizontal resolution: $2 \text{ m} \times 2 \text{ m}$.

$$U_{\text{ref}} = U_{\text{mag}, @ \text{ highest building}}$$



- Method: Modal approximation by proper orthogonal decomposition (POD)



➤ Estimation of an unknown wind field \tilde{X} :

- Reconstruction:
$$\tilde{X} = \Psi \cdot \tilde{A}(\varphi_{test})$$

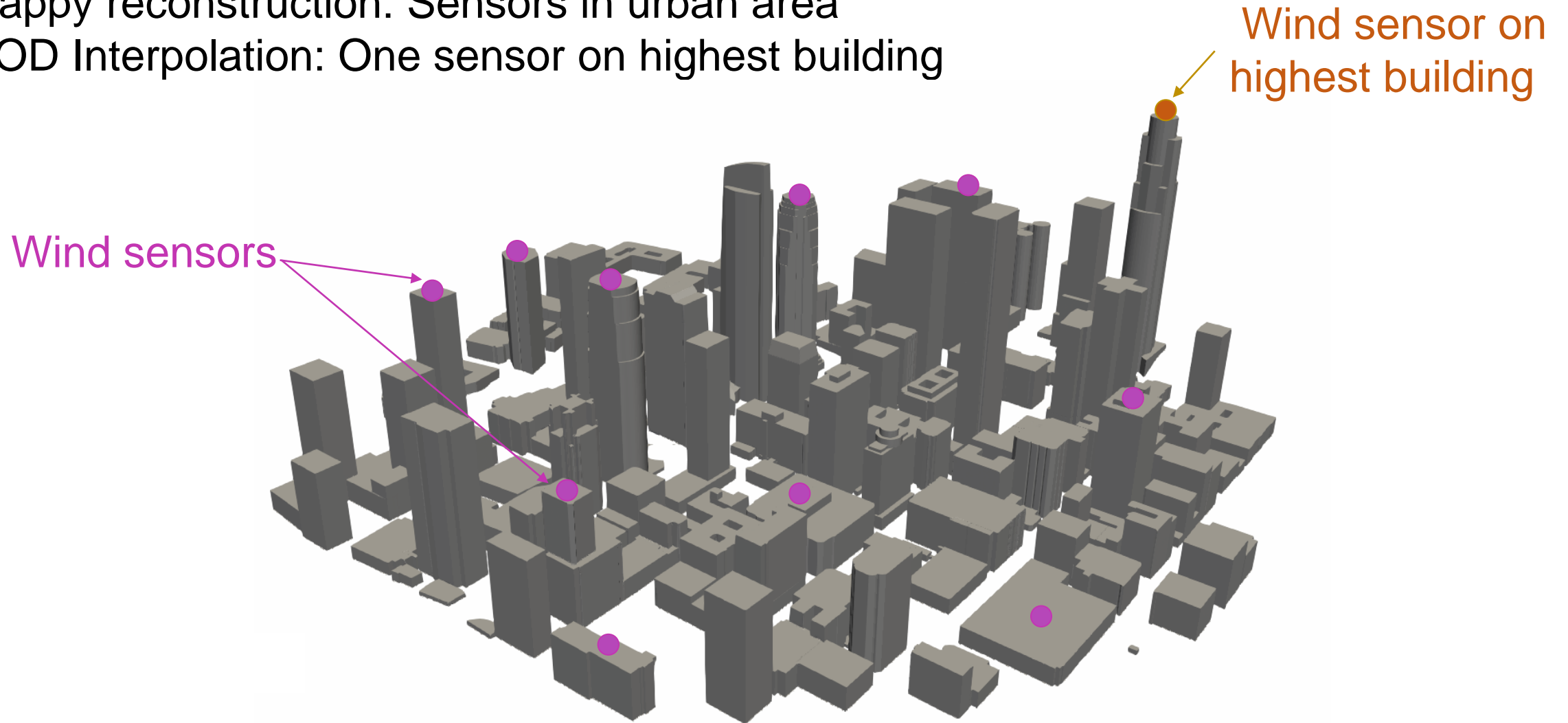
POD modes **Estimated POD coefficients**

- Extrapolation $U_{ref, test}$:
$$\tilde{X}_{U_{ref, test}} = [\tilde{X} + mean_{\varphi}(X)] \cdot U_{ref, test}$$

➤ Two options to estimate new POD coefficients \tilde{A} :

1. Gappy reconstruction with wind sensors measurements.
2. POD Interpolation as a function of the wind direction (if the φ_{test} is known).

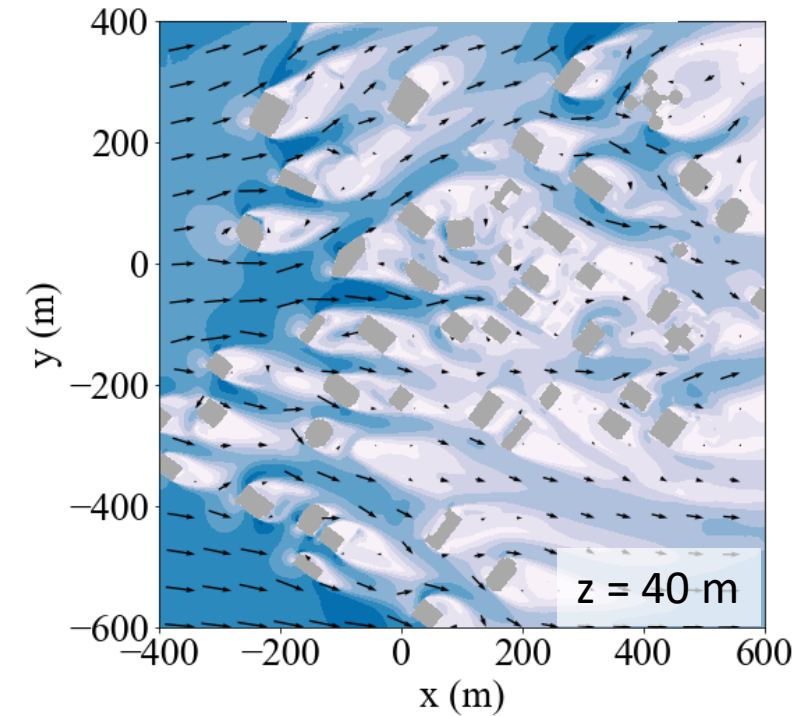
- Gappy reconstruction: Sensors in urban area
- POD Interpolation: One sensor on highest building



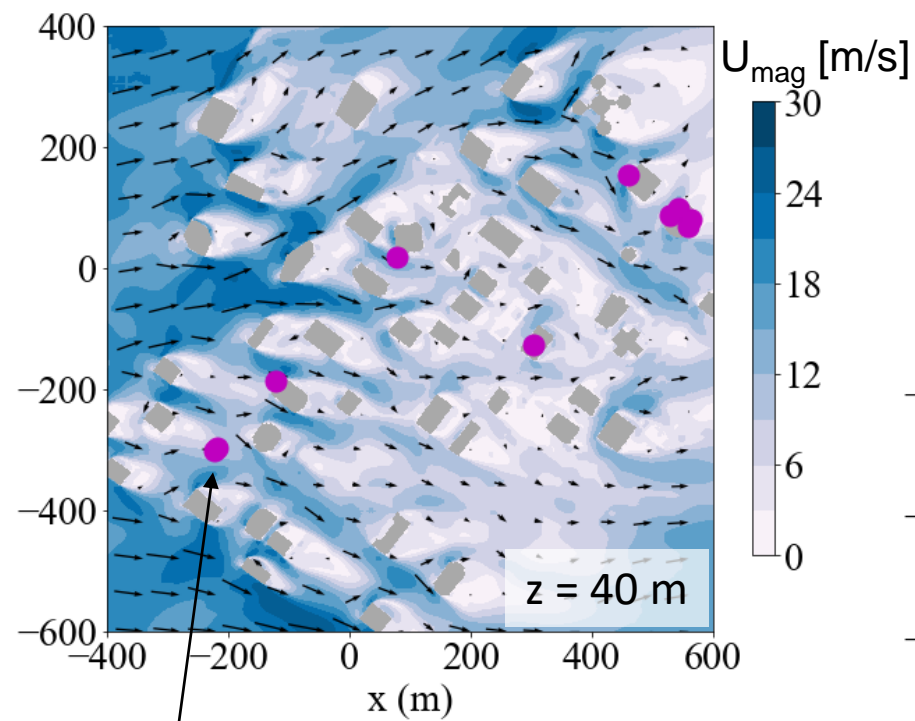
Gappy Reconstruction - U_{mag}

- Test case: $\varphi = 267^\circ$, $U_{ref} = 31 \text{ m/s}$
- Wind sensors = 10

Original

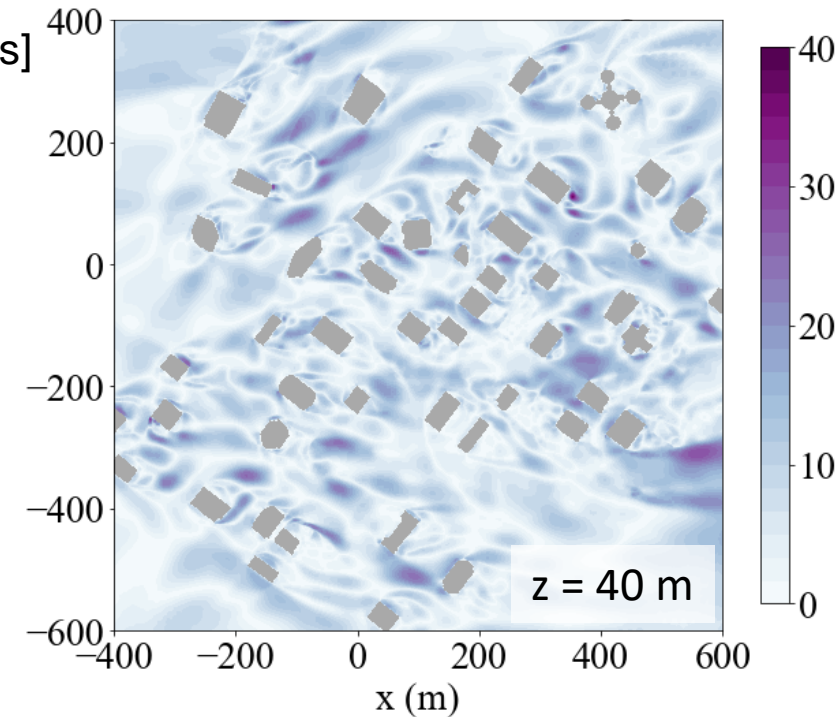


Reconstruction



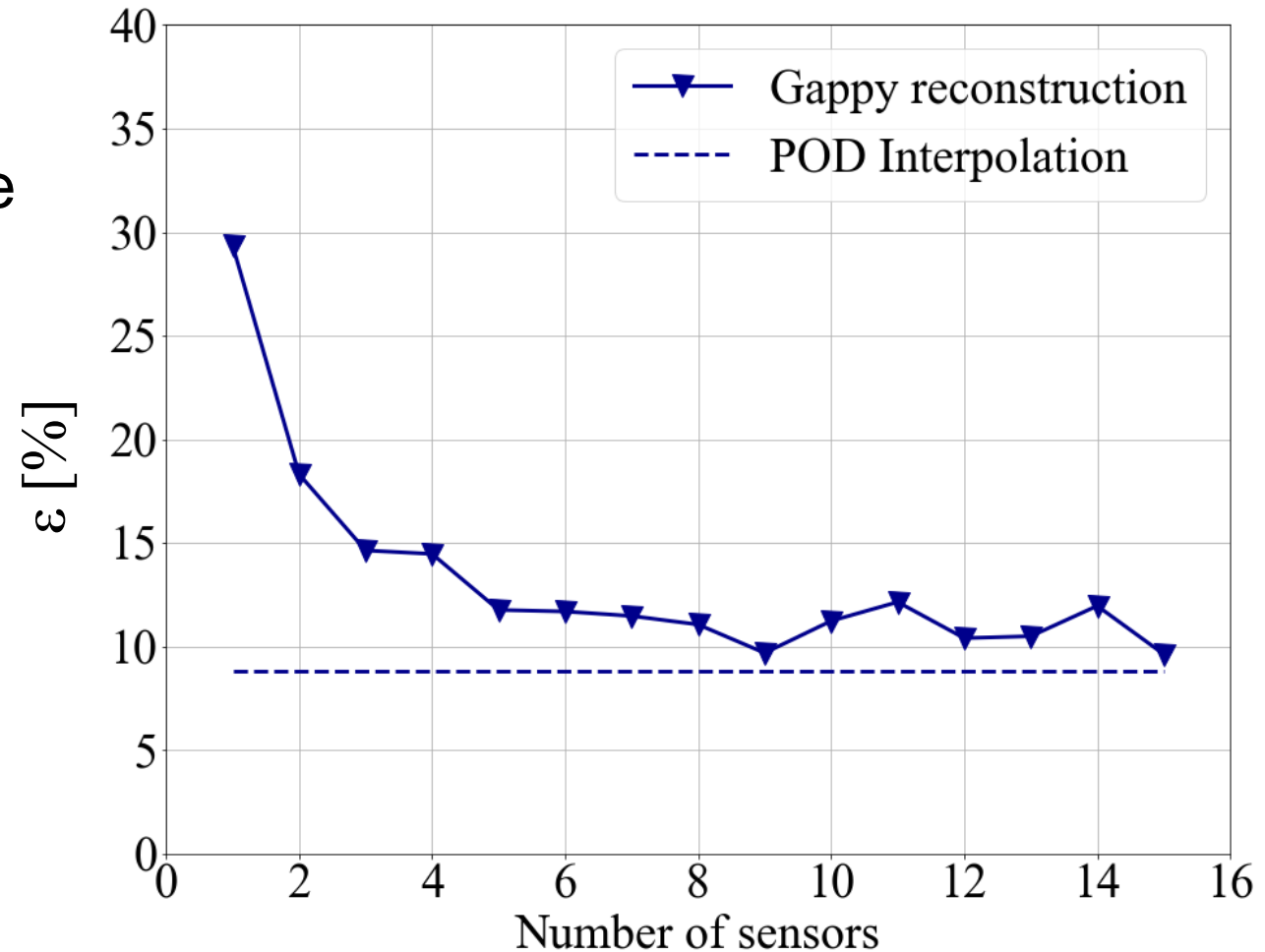
Sensors

Difference error =
 $(u_{orig} - u_{recon})/U_{ref} [\%]$



- Normalized root-mean-square reconstruction error:

$$\varepsilon = \frac{\|\tilde{X} - X_{orig}\|_2}{\|X_{orig}\|_2} \cdot 100 \%$$



- CFD simulation of urban area for different wind directions and wind speeds.
- 3D wind field estimation with high level of accuracy – Interpolation is slightly more accurate than the Gappy reconstruction.
- Both methods show a fast reconstruction time – suitable for urban air trajectory planning.
- Future: Improvement of interpolation with wind sensors measurements.